

## A Note on Jackknife Variance Estimation for the General Regression Estimator

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We derive in this article explicit jackknife variance estimators of the general regression estimator (*GREG*) using the random group technique. A corrected version is proposed that removes a large part of the positive model bias. A small simulation is presented.

*Key words:* Confidence interval; jackknife; regression estimator; survey sampling; variance estimation.

### 1. Introduction

Let  $U = \{1, \dots, N\}$  be a finite population. Suppose that we know the total  $T_x$  of an auxiliary variable  $x$  of dimension  $p$ . A sample  $s$  is observed from a  $\pi ps$  sampling plan. Let  $\pi_k$  and  $\pi_{kl}$  be the first and second inclusion probabilities, respectively. Our goal is to estimate the total  $T_y = \sum_U y_k$  of a positive variable  $y$  with  $\{(x_k, y_k), k \in s\}$  and  $T_x$ .

The general regression estimator (*GREG*) of  $T_y$  is given by

$$\hat{T}_{GREG} = \sum_s d_k g_{ks} y_k$$

where

$$g_{ks} = 1 + (T_x - \hat{T}_{x\pi})' \left( \sum_s d_k x_k x_k' / c_k \right)^{-1} x_k / c_k$$

is the ‘g-weight’,  $d_k = \pi_k^{-1}$  is the sampling weight,  $\hat{T}_{x\pi} = \sum_s x_k / \pi_k$  is the Horvitz-Thompson estimator of  $T_x$ , and  $c_k$  is chosen by the user. Särndal (1996) discusses the choice of  $c_k$ .

The asymptotic variance *AV* for the *GREG* is given by

$$AV(\hat{T}_{GREG}) = \sum_U \sum_U \Delta_{kl} \check{E}_k \check{E}_l$$

where  $E_k = y_k - x_k' B$ ,  $B = (\sum_U x_k x_k' / c_k)^{-1} \sum_U x_k y_k / c_k$ ,  $\Delta_{kl} = \pi_{kl} - \pi_k \pi_l$  and  $\check{E}_k = E_k / \pi_k$ .

Since the asymptotic variance is an ordinarily unknown quantity, Särndal et al. (1989)

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suggested the following  $g$ -weighted variance estimator given by

$$\hat{V}_g = \hat{V}_g(\hat{T}_{GREG}) = \sum_s \sum_k \check{\Delta}_{kl}(g_{ks}\check{e}_{ks})(g_{ls}\check{e}_{ls}) \quad (1)$$

where  $e_{ks} = y_k - x'_k \hat{B}_s$ ,  $\hat{B}_s = (\sum_s d_k x_k x'_k / c_k)^{-1} \sum_s d_k x_k y_k / c_k$ ,  $\check{\Delta}_{kl} = \Delta_{kl} / \pi_{kl}$  and  $\check{e}_{ks} = e_{ks} / \pi_k$ . With  $\hat{V}_g$ , we can construct a confidence interval for  $T_y$  given by  $\hat{T}_{GREG} \pm z_{1-\alpha/2} [\hat{V}_g]^{1/2}$ , that is expected to be valid approximately to the  $1 - \alpha$  confidence level.

The jackknife technique is another popular method to obtain a variance estimator. That method is described in Wolter (1985) and Särndal et al. (1992, chap. 11). We derive in the next section explicit jackknife variance estimators of the *GREG*. A corrected version is proposed that removes a large part of the positive model bias in Section 3. A small simulation is given in Section 4 to illustrate the proposed estimator. We conclude with a discussion in Section 5.

## 2. Jackknife Variance Estimation

In this section, we obtain explicit formulas for the jackknife variance estimators of the *GREG*. Let the sample be divided into  $A$  groups of size  $m$  partitioning the sample, where  $Am = n$ , where  $n$  is the sample size. The two jackknife variance estimators advocated by Särndal et al. (1992) are given by

$$\hat{V}_{JK1} = \frac{A-1}{A} \sum_{a=1}^A (\hat{T}_{GREG}(a) - \hat{T}_{GREG,JK})^2$$

$$\hat{V}_{JK2} = \frac{A-1}{A} \sum_{a=1}^A (\hat{T}_{GREG}(a) - \hat{T}_{GREG})^2$$

where  $\hat{T}_{GREG}(a)$  is the *GREG* calculated without the group  $a$  and

$$\hat{T}_{GREG,JK} = \frac{1}{A} \sum_{a=1}^A \hat{T}_{GREG}(a)$$

Since the two formulas  $\hat{V}_{JK1}$  and  $\hat{V}_{JK2}$  are related by the following relation

$$\hat{V}_{JK1} = \hat{V}_{JK2} - (A-1)(\hat{T}_{GREG} - \hat{T}_{GREG,JK})^2 \quad (2)$$

we can conclude that  $\hat{V}_{JK1} \leq \hat{V}_{JK2}$  and it is easy to pass from one form to the other. In practice, the two formulas give very similar results.

We consider in the following the maximal number of groups, that is the case  $A = n, m = 1$ . See the remark 11.5.3 of Särndal et al. (1992, pp. 441–442). With that hypothesis, we now use the random group technique to obtain explicit formulas for  $\hat{V}_{JK2}$  and for  $\hat{V}_{JK1}$  using Expression (2). Under that technique, we suppose that conditional on  $s$ , each group  $\{i\}$  is obtained by simple random sampling. In that case, there are  $n$  random subsamples  $s_{(i)} = s - \{i\}$ . The inclusion probability that the unit  $k$  will be in the final subsample, denoted  $\pi_k(i)$ , is  $\pi_k(i) = (n-1)/n\pi_k$ . Using that technique, we obtain the following result:

**PROPOSITION 1.** *The jackknife variance estimator  $\hat{V}_{JK2}$  of the *GREG* estimator is*

given by

$$\hat{V}_{JK2} = \frac{n}{n-1} \sum_s (\tilde{g}_{is} \check{e}_{is} - n^{-1} \hat{T}_{e\pi})^2 \quad (3)$$

where  $\tilde{g}_{is} = (g_{is} - n^{-1} T_x' M_s^{-1} x_i / c_i) / (1 - h_i)$ ,  $\hat{T}_{e\pi} = \sum_s e_{ks} / \pi_k$ ,  $h_i = d_i x_i' M_s^{-1} x_i / c_i$ ,  $e_{is} = y_i - x_i' \hat{B}_s$ ,  $M_s = \sum_s d_k x_k x_k' / c_k$

*Proof.* Let  $s_{(i)}$  denote the sample  $s$  without unit  $i$ . Since

$$\begin{aligned} \hat{T}_{GREG} &= \sum_s d_k g_{ks} y_k \\ &= \hat{T}_{y\pi} + (T_x - \hat{T}_{x\pi})' \hat{B}_s \end{aligned}$$

the GREG without unit  $i$  can be written as

$$\hat{T}_{GREG}(i) = \hat{T}_{y\pi}(i) + (T_x - \hat{T}_{x\pi}(i))' \hat{B}_s(i)$$

where  $\hat{T}_{y\pi}(i) = \sum_{s(i)} y_k / \pi_k(i)$  and similarly for  $\hat{T}_{x\pi}(i)$ , and

$$\hat{B}_s(i) = \left\{ \sum_{s(i)} x_k x_k' / (c_k \pi_k(i)) \right\}^{-1} \sum_{s(i)} x_k y_k / (c_k \pi_k(i))$$

With some algebra, we can show that

$$\hat{T}_{GREG}(i) = \hat{T}_{GREG} + \frac{1}{n-1} \sum_s e_{ks} / \pi_k - \frac{n}{n-1} (g_{is} - n^{-1} T_x' M_s^{-1} x_i / c_i) \check{e}_{is} / (1 - h_i)$$

Finally, using the relation 2, we obtain the following corollary

**COROLLARY 1.**

$$\hat{V}_{JK1} = \hat{V}_{JK2} - \frac{1}{n-1} (\hat{T}_{e\pi} - \sum_s \tilde{g}_{is} \check{e}_{is})^2$$

It is interesting to note that with the exception of the factor  $\tilde{g}_{is}$ , Formula 3 looks like the simplified variance estimator  $\hat{V}_0$  of Särndal et al. (1992, ex. (11.2.6), p. 422), where  $e_{is}$  now replaces  $y_i$ .

### 3. Corrected Estimator for the Model Bias

Särndal et al. (1992) note that, with the exception of the Horvitz-Thompson estimator, there are no exact results concerning the properties of the jackknife variance estimator. We study in this section the model bias of the Formula 3. Let the  $\xi$  regression model for  $y_1, \dots, y_N$  be given by

$$y_k = x_k' \beta + \epsilon_k$$

where the  $\epsilon_k$  are independent under the model, and such that  $E_\xi(\epsilon_k) = 0$ ,  $V_\xi(\epsilon_k) = \sigma^2 c_k$ , where  $E_\xi$  and  $V_\xi$  indicate the mean and variance under the model. We assume like Särndal et al. (1989) that for some  $\lambda$  independent of  $k$

$$c_k = \lambda' x_k \quad (4)$$

and we similarly define the *prototype*  $\hat{V}^*$  for  $\hat{V}_g$  as

$$\hat{V}^* = \sum_s \sum_k \check{\Delta}_{kl}(g_{ks}\check{\epsilon}_k)(g_{ls}\check{\epsilon}_l)$$

Särndal et al. (1992, p. 232) give several examples of variance structures satisfying Condition (4). Note that under that condition we have  $\sum_s e_{ks}/\pi_k = 0$ . We now recall a result that will be useful in the sequel.

**LEMMA 1.** *Under the model  $\xi$ , for any given realized sample  $s$ , the model mean, the model mean squared error and the relative model bias of the prototype  $\hat{V}^*$  are given by*

$$\begin{aligned} (i) \quad E_{\xi}(\hat{V}^*) &= \sigma^2 \left( \sum_s g_{ks}^2 c_k / \pi_k^2 - \sum_U g_{ks} c_k \right) \\ (ii) \quad MSE_{\xi}(\hat{T}_{GREG}) &= E_{\xi}(\hat{T}_{GREG} - T_y)^2 = \sigma^2 \left( \sum_s g_{ks}^2 c_k / \pi_k^2 - \sum_U c_k \right) \\ (iii) \quad RMB_{\xi}(\hat{V}^*) &= \frac{E_{\xi}(\hat{V}^*) - MSE_{\xi}(\hat{T}_{GREG})}{MSE_{\xi}(\hat{T}_{GREG})} = \frac{-\sum_U (g_{ks} - 1)c_k}{\sum_s g_{ks}^2 c_k / \pi_k^2 - \sum_U c_k} \end{aligned}$$

*Proof.* See Särndal et al. (1989).

We study properties of the jackknife variance estimator *prototype*. Under Condition (4), it is given by

$$\hat{V}_{JK2}^* = \frac{n}{n-1} \sum_s \check{g}_{ks}^2 \check{\epsilon}_k^2$$

Under the model, note that  $E_{\xi}(\hat{V}_{JK2}^*) = n/(n-1) \sigma^2 \sum_s \check{g}_{ks}^2 c_k / \pi_k^2 = A_s$ . Suppose that all  $h_i$  are negligible (their sample mean is  $n^{-1} \sum_s h_i = p/n$ ). Then  $g_{ks} \approx \check{g}_{ks}$  and  $A_s$  will be of the same order that the first term in the right member of (i) in the lemma. We have approximately

$$E_{\xi}(\hat{V}_{JK2}^*) - E_{\xi}(\hat{V}^*) \approx \sigma^2 \sum_U g_{ks} c_k$$

suggesting that the jackknife variance estimator overestimates the true variance, which is well-known. The relative model bias of the jackknife variance estimator can also be calculated using (ii) in the lemma:

$$RMB_{\xi}(\hat{V}_{JK2}^*) \approx \frac{\sum_U c_k}{\sum_s g_{ks}^2 c_k / \pi_k^2 - \sum_U c_k} \quad (5)$$

Looking at the numerator of 5, the relative model bias  $RMB_{\xi}(\hat{V}_{JK2}^*)$  is expected to be more important than for  $\hat{V}_g$ . It may however be small if the first term in the denominator dominates the second term in Formula (5). It can be seen that under simple random sampling, if the sampling fraction  $f = n/N$  is small, then  $RMB_{\xi}(\hat{V}_{JK2}^*)$  can be negligible.

However, since the positive bias may be more important in practice, we consider the following modification:

$$\hat{V}_{JK3}^* = \frac{n}{n-1} \sum_s (1 - \pi_k) \check{g}_{ks}^2 \check{\epsilon}_k^2 \quad (6)$$

We can justify that modification with the following argument. Under the model, we now obtain

$$E_{\xi}(\hat{V}_{JK3}^*) = A_s - \frac{n}{n-1} \sigma^2 \sum_s \tilde{g}_{ks}^2 c_k / \pi_k \tag{7}$$

If  $g_{ks} \approx \tilde{g}_{ks}$ , then the second term of that right member of Expression (7) will be of the same order as that for the second member of (i) in the lemma since  $\sum_s \tilde{g}_{ks}^2 c_k / \pi_k = \sum_U g_{ks} c_k$  (see Särndal et al. (1989, Expression 5.6)). Note that in the case of the simple random sampling,  $\hat{V}_{JK3}^*$  is simply  $\hat{V}_{JK2}^*$  affected by the finite population correction. However, our analysis is in the more general setting of a  $\pi ps$  sampling plan. Wolter (1985) discusses some methods to remove the bias of the jackknife variance estimator in the Horvitz-Thompson case. See also Särndal et al. (1992, pp. 439–440). These ideas are applied here to the *GREG*.

#### 4. Illustration

We consider a small Monte Carlo simulation for the variables  $y = RMT85 \times 10^{-4}$ ,  $x_1 = CS82$  and  $x_2 = SS82$  for the *MU281* population (of size  $N = 281$ ) in Särndal et al. (1992). This study is a complement to the one in Särndal et al. (1992, pp. 278–280). Like them, we carried out 5,000 repeated simple random samples, each with size  $n = 100$ . The main objective of the simulation study is to evaluate coverage properties of confidence intervals at the 95% level

$$\hat{T} \pm 1.96[\hat{V}(\hat{T})]^{1/2}$$

where  $\hat{T}$  is the *GREG* estimator, and  $\hat{V}(\hat{T})$  is a variance estimator. We consider the *GREG* estimator with only  $x_1$ , the *GREG* estimator with only  $x_2$ , and the *GREG* estimator with  $x_1$  and  $x_2$ . We always included an intercept and let  $c_k \equiv 1$  throughout the study. We consider the variance estimator given in Formula (1), the jackknife variance estimators given in Formula (3) and the corrected Version (6). Formula (1) becomes under simple random sampling

$$\hat{V}_g = N^2 \left( \frac{1}{n} - \frac{1}{N} \right) \frac{\sum_s g_{ks}^2 e_k^2}{n-1}$$

Results are presented in Table 1, where  $\tilde{T}$  and  $S_{\tilde{T}}^2$  are the sample mean and sample variance of the 5,000 estimates  $\hat{T}$ ;  $\tilde{V}_g$ ,  $\tilde{V}_{JK2}$  and  $\tilde{V}_{JK3}$  are the sample means of the 5,000 variance estimates,  $\hat{V}_g$ ,  $\hat{V}_{JK2}$  and  $\hat{V}_{JK3}$ , respectively; and  $ECR_g$ ,  $ECR_{JK2}$  and  $ECR_{JK3}$  are the respective coverage rates for the *GREG* based on  $\hat{V}_g$ ,  $\hat{V}_{JK2}$ ,  $\hat{V}_{JK3}$ , respectively. The final column gives the approximate variance for  $\hat{T}$  given by

$$AV(\hat{T}) = N^2 \left( \frac{1}{n} - \frac{1}{N} \right) \frac{\sum_U E_k^2}{N-1}$$

The results in Table 1 show that in our experience,  $\hat{V}_{JK3}$  gives good coverage properties and in the three cases the variance of the 5,000 estimates is close to  $\tilde{V}_{JK3}$ . In that limited simulation,  $\hat{V}_{JK3}$  seems to compare reasonably well with  $\hat{V}_g$ .

#### 5. Discussion

In this article, explicit jackknife *GREG* variance estimators are exhibited. These formulas give new examples of the well-known rule of thumb that jackknifing leads to

Table 1. Results of the simulation

Estimator	$\bar{\hat{T}}$	$S_{\hat{T}}^2$	$\bar{\hat{V}}_g$	$ECR_g$	$\bar{\hat{V}}_{JK2}$	$ECR_{JK2}$	$\bar{\hat{V}}_{JK3}$	$ECR_{JK3}$	AV
$\hat{T}_{GREG}(x1)$	5.31	0.122	0.115	0.937	0.189	0.977	0.121	0.942	0.116
$\hat{T}_{GREG}(x2)$	5.30	0.124	0.118	0.934	0.191	0.978	0.123	0.941	0.117
$\hat{T}_{GREG}(x1, x2)$	5.31	0.056	0.052	0.929	0.088	0.978	0.057	0.939	0.052

Note: The total  $T_y$  is 5.315.

overestimation of the variance. An idea for possible overestimation “correction” is presented, leading to a modified estimator. In the numerical illustration, we obtain reasonable properties with the corrected version. We do not claim that the proposed estimator is superior to other estimators. In fact, in a vast majority of situations occurring in practice,  $\hat{V}_g$  may be preferable. Jackknife estimators are perhaps applicable to exceptional situations (shortage of time, one-time use, etc). It seems to appear that their chief merit is that they require less programming efforts. For example, there is no need to evaluate all the  $\pi_{kl}$  as in  $\hat{V}_g$ . See Särndal (1996) for a discussion of this problem. However, if jackknife variance estimators for the *GREG* are needed, it is hoped that Proposition 1 will be useful.

## 6. References

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